Mobile Robots

LD Series

Autonomous Intelligent Vehicles (AIVs), self-mapping, self-navigating.

- Natural-feature navigation:
- Automatically plans routes to prevent collisions
- Fleet management:
 - Supervises and coordinates the entire fleet of up to 100 vehicles
- Easy deployment:
 - Short installation time, no facility modifications



Ordering Information

Mobile Robots-LD Platform

Appearance	Product Type	Product Name	Maximum Load	Maximum Speed		Configuration & Attachment		
					Standard	-		37032-00000
				1.8 m/s	Docking station kit	Docking station Battery power cable (0.45 m)	: 12477-000 : 12676-000	37032-00002
6MROD	OEM*	LD-60	60 kg		Starter kit	Docking station Battery power cable (0.45 m) MobilePlanner software license Joystick Top plate	: 12477-000 : 12676-000L : 13495-200 : 13558-000 : 12944-000	37032-10004
	OEIVI				Standard	-		37042-00000
					Docking station kit	Docking station Battery power cable (0.45 m)	: 12477-000 : 12676-000	37042-00002
		LD-90	90 kg	1.35 m/s	Starter kit	Docking station Battery power cable (0.45 m) MobilePlanner software license Joystick Top plate	: 12477-000 : 12676-000L : 13495-200 : 13558-000 : 12944-000	37042-10004
	Cart	LD-105CT	105 kg	1.35 m/s	Standard	Touchscreen Side laser	:13605-000 :13456-000	37141-00010
					Docking station kit	Touchscreen Side laser Docking station Battery power cable (0.45 m)	:13605-000 :13456-000 :12477-050 :12676-000	37141-00012
					Starter kit	Touchscreen Side laser Docking station Battery power cable (0.45 m) MobilePlanner software license Acuity localization Joystick Cart	:13605-000 :13456-000 :12477-050 :12676-000L :13495-200 :13700-000 :13558-000 :75020-000	37141-01014
Ottoon	Transporter			0.9 m/s	Standard	Touchscreen Side laser	:13605-000 :13456-000	37161-00010
		LD-130CT 130			Docking station kit	Touchscreen Side laser Docking station Battery power cable (0.45 m)	:13605-000 :13456-000 :12477-050 :12676-000	37161-00012
			130 kg		Starter kit	Touchscreen Side laser Docking station Battery power cable (0.45 m) MobilePlanner software license Acuity localization Joystick Cart	:13605-000 :13456-000 :12477-050 :12676-000L :13495-200 :13700-000 :13558-000 :75020-000	37161-01014

^{*} Also available in ESD versions (built in accordance with the IEC 61340-5-1 standard).

Software/Controller

Appearance	Product Name	Configuration & Attachment	Model
and the state of t	MobilePlanner	Installer (USB)* License dongle	13495-200
1 - 1 - MAN	Enterprise Manager 2100	License dongle	11168-200

^{*} The latest version of MobilePlanner can be downloaded from Omron Adept Technologies Inc. website. http://www.adept.com/Robots-Mobile

Options

Appearance	Product Name	Specification	Configuration & Attachment	Model
		Single sensor	Sensor \times 1, mounting bracket \times 1, power connector \times 1, RS-232 connector \times 1, 25 mm wide magnetic tape (south top side, 50 m roll)	13660-100
	High Accuracy Positioning System	Double sensor	Sensor \times 2 , mounting bracket \times 2, power connector \times 1, RS-232 connector \times 2, 25 mm wide magnetic tape (south top side, 50 m roll)	13660-000
		Magnetic tape	25 mm wide magnetic tape (south top side, 50 m roll)	14925-000
	Acuity Localization	-	Camera, mounting kit, cables, leveling kit	13700-000
00000	Touchscreen	-	Touchscreen with bracket, power supply with bracket, power cable from core to power supply (33 cm), power cable from power supply to touchscreen (183 cm), Ethernet cable between touchscreen and core (153 cm), gasket between touchscreen and AIV mounting surface, software package including touchscreen support	13605-000
		Bundle	Laser × 2, cable × 1 (Y cable for 2 lasers)	13456-000
	Side Laser	Kit	Laser \times 2, Cable \times 1 (Y cable for 2 lasers), mounting kit \times 2, metal cover \times 2	13456-100
OMRON ON THE STATE OF THE STATE	Call/Door Box	WiFi Wired	Call/door box, cable	13029-802

Accessories

Appearance	Product Name	Specification	Configuration & Attachment	Model
	Battery	-	-	18578-000
		-	Docking station, AC power cable	12477-000
Docking Station	Docking Station	Extended Wall mount	Docking station, AC power cable, extended wall mount (for Cart Transporter)	12477-050
	Joystick	Cable length: 0.6 to 3 m	-	13558-000
-	Breakout Cable	-	DB44HD breakout cable (D-SUB44 pin cable for digital I/O interface)	14165-000

Appearance	Product Name	Specification	Configuration & Attachment	Model
-	Top Plate	Top cover for OEM type	-	12944-000
	Cart	-	-	75020-000
-	Battery Power Cable	Cable length: 0.45 m	-	12676-000L

Specifications

Mobile Robots-LD Platform General Specifications

lhom		ОЕМ		Cart Transporter		Note	
	Item		37042-xxxxx	37141-xxxxx	37161-xxxxx	Note	
Materials		KYDEX					
Dimension (L × W × H)		699 × 500 × 383 mm		894 × 1074 × 1394 mm*		* Height includes WiFi antenna	
Weight (with Battery)		62 kg		81 kg (Vehicle)/23 kg (Cart)			
	Ambient temperature	5 to 40 °C					
	Ambient humidity	5 to 95 % (non-con	densing)				
Environment	Operating Environment	Indoor usage only,	no excessive dust, r	no corrosive gas		Direct sunlight may cause safety laser false positive	
	IP rating	IP20					
	Cleanroom rating	Fed Class 100, ISC	Class5	None			

AIV (Autonomous Intelligent Vehicle) Specifications

	No	0	EM	Cart T	ransporter	Nete
	Item	37032-xxxxx	37042-xxxxx	37141-xxxxx	37161-xxxxx	Note
	Floor Requirements	Level surface or co	oncrete (no water, n			
Floor Conditions	Minimum floor flatness	F _F 25 (ACI 117 star	ndard)*		* ACI 117 is the American Concrete Institute standard for concrete floors. FF is flatness, FL is the level. Higher FF numbers represent flatter floors. FF25 is a fairly lenient specification.	
	Traversable step	15 mm max.* ¹	10 mm max.* ¹	5 mm max.*2	5 mm max.*2	*1 A speed of 250-300 mm/s and 250 mm/s, for the LD-60 and LD-90, is required for these steps. Faster or frequent driving over such steps or gaps will shorten the lifespan of the drivetrain components. Lower speeds may not traverse the step. Steps
	Traversable gap	15 mm max.	15 mm max.	5 mm max.*2	5 mm max.*2	should have smooth, rounded profil *2 The Cart Transporter with a cart capable of driving over a gap or step 5 mm at a speed of 250 mm/s, but the should not be regarded as normal under Regular driving over such gaps or steps will shorten the lifespan of the drivetrain components.
	Climb grade	Below 1: 12 (60 kg Flat floor only (ove	g max.) er 60 kg)	'		
N	Routing	Autonomous routin	ng by localizing with bing			
Navigation	Environmental map making method	Scan by walking the data in the Mobilel	e mobile robot throu Planner			
Payload	Maximum Weight	60 kg	90 kg	105 kg*	130 kg*	* Excluding cart weight
	Maximum Speed	1800 mm/s	1350 mm/s	1350 mm/s	900 mm/s	
Mobility	Maximum Rotation Speed	180°/s	180°/s	100°/s	'	
	Stop Position Accuracy	± 100 mm position	*, ± 2° rotation	* ±10 mm position, ±0.5° rotation with option, (High Accuracy Positioning System)		
5	Materials	Non-marking nylor	n foam-filled rubber,	non-conductive		
Drive wheel	Size	200 dia. × 50 mm	nominal, 2 wheels			
	Materials	Conductive thermo	oplastic rubber on p	olyolefin		
Passive caster	Size	75 dia. × 41 mm n	ominal, 4 casters			

	n	0	EM	Cart Transporter		N. I.
	Item	37032-xxxxx	37042-xxxxx	37141-xxxxx	37161-xxxxx	Note
	Battery	22-30 VDC				
	Capacity	72 Ah Battery cell	nominal capacity			
	Run Time	15 hours (continue	ous) approx.	With no payload condition		
	Recharge Time	4 hours (5:1 ratio)	approx.			
	Battery Life Cycles	2,000 recharge cy	cles (battery cell nor	ninal)		
Power	Charging Method	Automatic / manua	al			
	Auxiliary Power	12 VDC±5%, 1 A s	switched*			5, 12, 20, and 22-30 VDC power can be provided to external devices * 10 A switched and 10 A safe, switched share the 10 A of current
0: 1 1	Safety Standard	EN1525 / JIS D68	02 / ANSI B56.5			
Standard	Wireless	IEEE 802.11 a/b/g				
	Safety Scanning Laser	1 at front Class 1 PLd safety per ISO 15 m maximum ra 240° field of view				
	Emergency Stop	1 at operator panel 1 at HMI post touchscreen, 1 at operator panel				
	Rear Sonar	2 at rear, 2 m rang	e	Each pair includes one emitter and one receiver working together		
	Front Bumper	1 at front of platfor	m, 2 pairs of sensor			
Safety Features	Low Front Laser	1 at front of platform Class 1 4 m maximum range 126° field of view				
	Side Laser	Option* 2 on horizontal tubes of HMI post Class 1 4 m maximum range 270° field of view			* 2 on sides of payload structure, user- mounted	
	Flash Light	Light disc in each side Light disc in each side, beacon on HMI post				
	Speaker	3.5 in., 80 W max.				
	Screen / Touch Panel	3.5 in. TFT 320 × 2 color screen	240 pixels, 256 K	7.0 in. TFT LCD tou RGB	ch panel, 18/24 bit	
Operator Interface	Button	On button: green Off button: red Brake-release butt Keyswitch (disable		On button: green Off button: red Brake-release butto Keyswitch (disabled Latch button, unlate	off button),	
	Wireless	IEEE 802.11 a/b/g		1		
	Ethernet Port	1 × user LAN, 1 ×	maintenance LAN, A	uto-MDIX		
	Serial	RS-232 × 2, CAN	Bus B × 1			
User I/F	Digital I/O	16 inputs, 16 outp	uts			
	Analog I/O	8 inputs (0 to 30 V), 4 outputs (0-20 V)			
	Audio		audio in / audio out			
Cart Latching	Latching Method	Not available		Automatic		

MobilePlanner				
Model	13495-200			
Operating System	Windows 7 (32-bit/64 bit version) Windows 8 (32-bit/64-bit version) Windows 10 (32-bit/64-bit version)			
CPU	1.5 GHz dual-core CPU recommended			
Main Memory	1.5 GB min. (4 GB min. recommended)			
Hard Disk	At least 200 MB of available space			
Video Memory	256 MB min.			
Display	XGA 1024 × 768, 16 million colors			
Communications Ports	USB port (for license key)			
Supported Languages	Japanese, English			

Enterprise Manager 2100

Litterprise manager 2	Litter prise manager 2100			
Model	11168-200			
Dimensions- W \times D \times H	430 × 492.8 × 43.2 mm			
Weight	9.1 kg			
Mounting method	1U rack mount in a standard 19-inch equipment rack			
Power Supply	100-240 VAC *			
Power Consumption	200W max.			
Operating Temperature	10 to 35 °C			
Storage Temperature	-25 to 60 °C			
Operating Humidity	8 to 90%, non-condensing			
Storage Humidity	5 to 95%, non-condensing			
Chassis protection class	IP20			
CPU	Intel® Xeon® CPU			
Main Memory	32 GB DDR3			
Storage	60 GB SSD			
Archive Storage	4 TB HDD			
Communication port	10/100/1000 Ethernet × 4, USB × 4, VGA			
Status Display	Multi-segment LCD			

^{*} typical 100 W

High Accuracy Positioning System

Model		13660-x00		
	Depth	30 mm		
Sensor	Width	160 mm		
	Rating	IP64		
0011001	Environment	-40 to 85 °C		
	LEDs	Power, tape present, left marker, right marker		
Magnetic Tape	Width	25 mm		
	Orientation	South up		
	Width	25 mm		
Markers	Length	300 mm min. for 500 mm/s drive speed		
(Magnetic Tape)	Orientation	North up		
	Separation From Tape	15 - 30 mm		
Connections	Front Sensor	RS232-1 (/dev/ttyUSB9) on the core		
	Rear Sensor	RS232-2 (/dev/ttyUSB10) on the core		
	Power, Both Sensors	Aux power using the included splitter cable		

Acuity Localization	
Model	13700-x00
Field of View	140°
Power Input	12 VDC (±10%) supplied from platform through

3.3 W maximum

Touchscreen

Power Consumption

Model	13605-000
Touch Panel	PCAP touch sensor, 5 simultaneous touches, black-bordered cover lens
TFT Display TFT Display TFT LCD panel, 18/24 bit RGB parallel interface, 7.0 in. WVGA - wide viewing and 5-touch	
Backlight	Constant current LED supply
Power Input	5 VDC supplied through power connector
Power Consumption	6.5 W maximum

Call/Door Box

Cally Book		
Model	13029-802	
Dimensions- W \times D \times H	141.4 × 74.7 × 30 mm	
Weight	190 g	
Mounting method	Mount to the provided wall frame with four screws	
Power Supply	12 VDC	
Power Consumption	0.5 A, 6 W typical	
WiFi	IEEE 802.11 a/b/g/n	
Communication Port	Ethernet	
I/O	Input × 2, output × 2 (30 VDC, 2 A max.)	

Battery

Model	18578-000	
Run Time (No Payload)	15 hours (continuous) approx.	
Weight	19 kg	
Voltage	22-30 VDC	
Capacity	72 Ah (battery cell nominal)	
Recharge Time	4 hours approx.	
Life Expectancy	2,000 times 80% DOD (battery cell nominal), 7 years, approx., 16 hrs/day, 5 days/wk 4 years, approx., 19/7 (full-time)	

Docking Station	
Model	12477-0x0
Current	8 A*1
Contacts	2
Power	100 to 240 VAC, 50 to 60 Hz
Power Consumption	800 W
Humidity	5 to 95 %, non-condensing
Temperature	5 to 40° C
Dimensions (W \times D \times H)	349 × 369 × 315 mm (495 × 495.5 × 317 mm)* ²
Weight	8.2 kg
Mounting	Wall bracket, directly to floor, or on floor with floor plate
Indicators	Power on: blue Charging: yellow
Connector	For out-of-platform battery charging

^{*1} Thermal fuse in AC power switch (10 A time-lag fuse at switch for legacy dock)
*2 () for with floor plate

Joystick

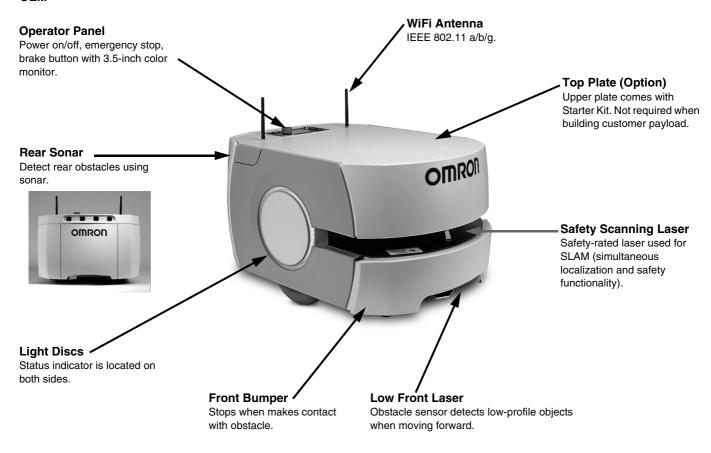
Model	13558-000
Weight	.55 kg
IP Rating	IP56

Cart

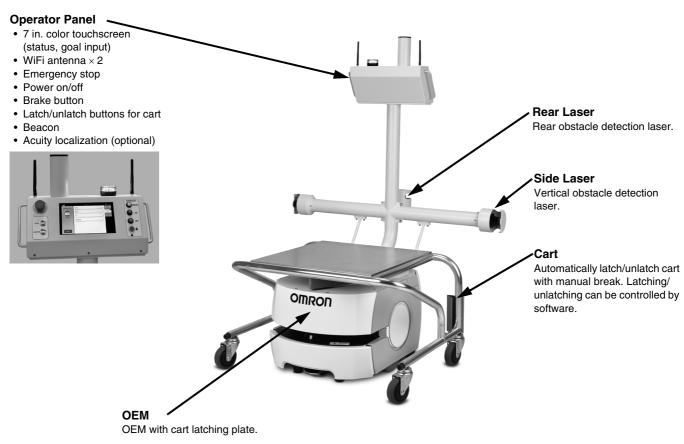
Model	75020-000
Dimensions (L \times W \times H)	592 × 846 × 480 mm
Weight	23 kg
Rating	ESP-rated
Passive Casters	2 front, 2 rear, spring-loaded
Caster Diameter	100 mm nominal
Caster Brakes	At 2 rear casters

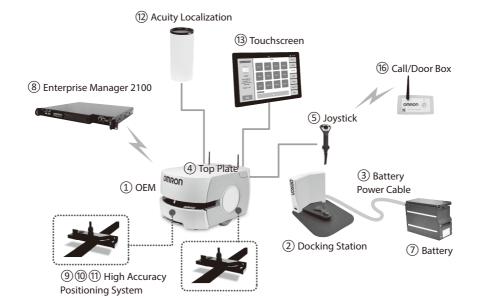
Components and Functions

OEM



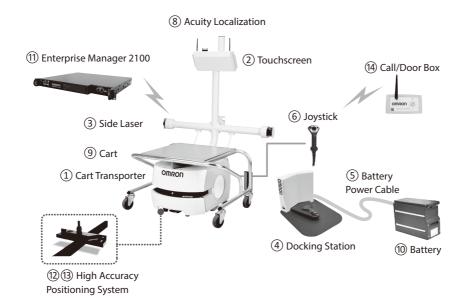
Cart Transporter





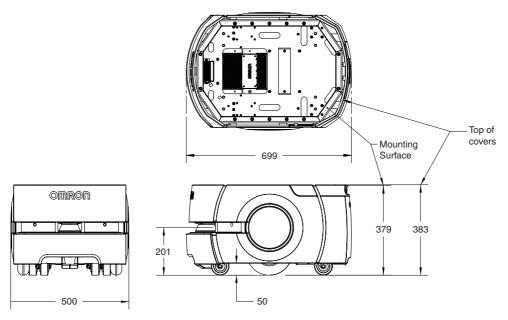
	Product Name	Model	Description	Docking Station Kit/Starter kit
1	OEM	370x2-00000	A mobile robot OEM. The battery is not included.	Included in docking station kit and starter kit
2	Docking Station	12477-000	A docking station to charge the battery installed in the mobile robot.	Included in docking station kit
3	Battery Power Cable	12676-000L	A cable to connect a battery and docking station to charge the battery outside of the mobile robot.	included in docking station kit
4	Top Plate	12944-000	A upper plate of the mobile robot OEM. It is not necessary for building customer payload.	
(5)	Joystick	13558-000	Used for manually controlling the mobile robot.	Included in starter kit
6	MobilePlanner	13495-200	PC software to configure, drive, and observe the mobile robot, including a USB license dongle.	
7	Battery	18578-000	A battery that is installed in the mobile robot.	-
8	Enterprise Manager 2100	11168-200	A system that manages a fleet of mobile robots, including a network appliance, software, and USB license dongle.	-
9	High Accuracy Positioning System (Single sensor)	13660-100	A combination of sensor and magnetic tape to achieve accurate alignment during forward driving motion, when the sensor is attached to mobile robot and magnetic tape is on the floor.	-
10	High Accuracy Positioning System (Double sensor)	13660-000	A combination of two sensors and magnetic tape to achieve accurate alignment during forward and backward driving motions, when the sensors are attached to mobile robot and magnetic tape is on the floor.	-
11)	Magnetic Tape	14925-000	Magnetic tape for the High Accuracy Positioning System. The tape is applied to signal the mobile robot where to stop.	-
12	Acuity Localization	13700-000	Used where process layout or obstacle location changes often. Installed on a payload structure attached to the mobile robot.	-
(13)	Touchscreen	13605-000	Allows operators to check the status of the mobile robot, enter goals, and pause the mobile robot. Installed on a payload structure attached to the mobile robot.	-
14)	Side Laser Bundle	13456-000	Used to detect obstacles that are at heights the safety scanning laser of the mobile robot cannot detect. Installed on a payload structure attached to the mobile robot.	-
15)	Side Laser Kit	13456-100	Includes the above mentioned side laser, mounting kit, and metal enclosures.	-
16	Call/Door Box	13029-802	Used to issue a request for a mobile robot to go to the goal or to open a closed door, usually installed at location of use.	-
17)	Breakout Cable	14165-000	A D-SUB44 pin cable for digital I/O interface of the mobile robot.	-

Cart Transporter

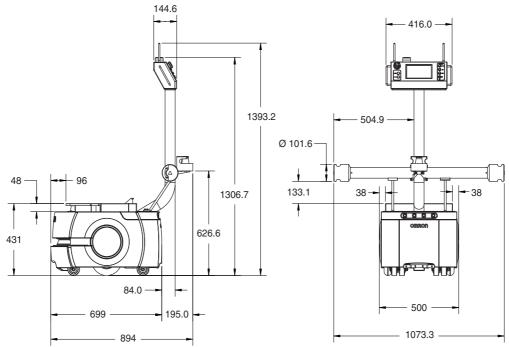


	Product Name	Model	Description	Docking Station Kit/Starter Kit
1	Cart Transporter	371x1-00000	A mobile robot cart transporter. The battery is not included.	
2	Touchscreen	13605-000	Allows operators to check the status of the mobile robot, enter goals, and pause the mobile robot. Installed on a payload structure attached to the mobile robot.	Included in docking station kit and starter kit
3	Side Laser	13456-000	Used to detect obstacles that are at heights the safety scanning laser of the mobile robot cannot detect. Installed on a payload structure attached to the mobile robot.	
4	Docking Station	12477-000	A docking station to charge the battery installed in the mobile robot.	Included in decline etation bit
(5)	Battery Power Cable	12676-000L	A cable to connect a battery and docking station to charge the battery outside of the mobile robot.	Included in docking station kit
6	Joystick	13558-000	Used for manually controlling the mobile robot.	
7	MobilePlanner	13495-200	PC software to configure, drive, and observe the mobile robot, including a USB license dongle.	Included in starter kit
8	Acuity Localization	13700-000	Used where process layout or obstacle location changes often. Installed on a payload structure attached to the mobile robot.	
9	Cart	75020-000	A cart designed to work seamlessly with the mobile robot cart transporter.	
10	Battery	18578-000	A battery that is installed in the mobile robot.	-
11)	Enterprise Manager 2100	11168-200	A system that manages a fleet of mobile robots, including a network appliance, software, and a USB license dongle.	-
12	High Accuracy Positioning System (Single Sensor)	13660-100	A sensor and magnetic tape to achieve accurate alignment when the mobile robot follows driving forward. The sensors are attached to the mobile robot.	-
13)	Magnetic Tape	14925-000	Magnetic tape for the High Accuracy Positioning System. The tape is applied to signal the mobile robot where to stop.	-
14)	Call/Door Box	13029-802	Used to issue a request for a mobile robot to go to the goal or to open a closed door. Installed at the goal or door.	-
15)	Breakout Cable	14165-000	A D-SUB44 pin cable for digital I/O interface of the mobile robot.	-

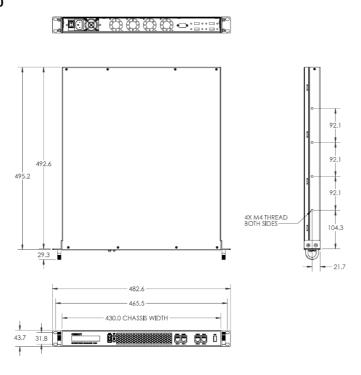
Mobile Robots-LD Platform OEM



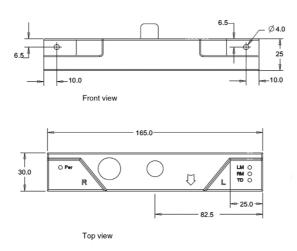
Cart Transporter



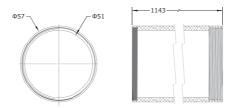
Enterprise Manager 2100



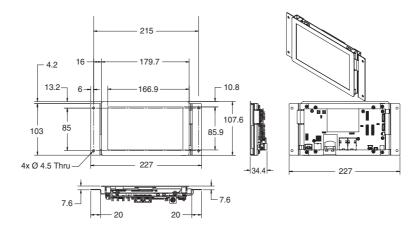
High Accuracy Positioning System



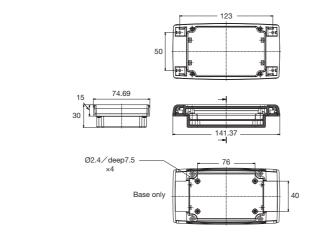
Acuity Localization



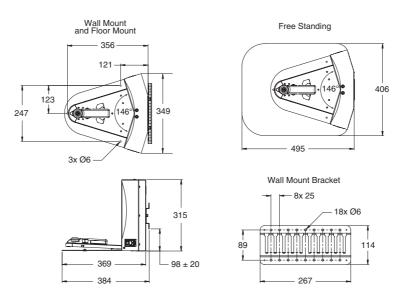
Touchscreen



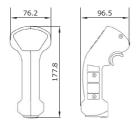
Call/Door Box



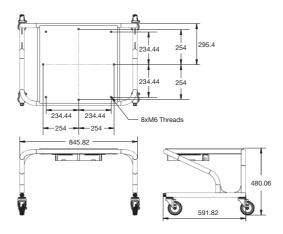
Docking Station



Joystick



Cart



Related Manuals

Manual No.	English Title	
l611	Mobile Robots LD Platform User Guide	
l612	Mobile Robots LD Cart Transporter User Guide	
I613	Mobile Robots LD Platform Peripherals Guide	
l614	Mobile Robots Software Suite User Guide	
l615	Enterprise Manager User Guide	
I616	Mobile Robot Safety Guide	
l617	Advanced Robotics Command Language Reference Guide	
I618	Advanced Robotics Command Language Enterprise Manager Integration Guide	

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